

MD2025.

International Conference on Machine Design 2025

Programme

11-12 SEPTEMBER 2025

Faculty of Engineering – University of Porto
Porto, Portugal



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Programme

Author name underlined → presenting author

Time	Thursday 11 September 2025	
08:40	MD2025 Opening (Room Bo32)	
	Session 1: Machine Automation & Testing I	
	(Chair: L. F. M. da Silva, University of Porto, Portugal; A. M. Lopes, University of Porto, Portugal)	
	Room Bo32	
09:00	PLENARY LECTURE: Design, Fabrication and Control of Soft Robot Actuators	
	<u>Pedro Neto</u> (Mechanical Engineering Department, University of Coimbra, Portugal)	
09:40	Modeling and Simulation of the Dynamics of Robotic Hand Grasping of Multiple Cylindrical Objects by a Discrete Element Method Approach	MD25_1
	Y. A. Caicedo, <u>L. E. Chiang</u> (Mechatronics Systems Lab, Santiago, Chile)	
10:00	Design and Validation of a Custom Apparatus for Cyclic Creep Testing of Pressure-Sensitive Adhesives	MD25_2
	<u>B. D. Simões</u> (Institute of Science and Innovation in Mechanical and Industrial Engineering (INEGI), Porto, Portugal), E. M. D. Fernandes, E. A. S. Marques, R. J. C. Carbas, S. Maul, P. Stihler, P. Weißgraebner, L. F. M. da Silva	
10:20	Developing Two Multiaxial Testing Machines to Measure Multiaxial Strength of Weak Snow Layers	MD25_3
	J. Schöttner (WSL Institute for Snow and Avalanche Research SLF, Flüelastrasse, Davos Dorf, Switzerland), E. Marques, B. Eggert, M. Walet, R. Carbas, V. Adam, M. Hohl, P. Weißgraebner, P. Rosendahl, M. Piecuch, S. Kraus, F. Rheinschmidt, M. Hedvard, L. F. M. da Silva, J. Schweizer, A. van Herwijnen	
10:40	COFFEE BREAK (Coffee Lounge)	
	Session 2: Machine Automation & Testing II	
	(Chair: Luciano Chiang, Mechatronics Systems Lab, Santiago, Chile; R. J. C. Carbas, INEGI, Porto, Portugal)	
	Room Bo32	
11:00	Motorcycle Model in Cornering Situation	MD25_4
	Massimo Cavacece (University of Cassino and Southern Latium, Cassino, Italy)	
11:20	Hydrodynamic Modeling and Field Evaluation of a Towed Underwater Vehicle	MD25_5
	<u>A. P. Carboni</u> (Federal University of Santa Catarina, Campus Joinville, Brazil), A. Z. Salvi, T. A. Fiorentin, F. K. Fiorentin, G. P. De Miranda, L. S. T. Matos, L. G. Barcaro, A. C. Fujarra	
11:40	Energy minimization in the control of servo-hydraulic systems using dynamics found in planet formation	MD25_45
	<u>Rodrigo M. C. Bernardo</u> (Mechanical Engineering Department, University of Aveiro, Portugal), Marco P. Soares dos Santos	
12:00	Modular Learning Platform for Industrial Automation Using OMRON Systems: A Hands-On Approach to Industry 4.0 Technologies	MD25_7
	<u>Filipe Pereira</u> (School of Engineering of Porto (ISEP), Polytechnic of Porto, Portugal), Adriano Santos, António Silva, Carlos Felgueiras, and António Ramos	
12:20	An Analytical and Experimental Approach for Characterizing Vibration Attenuation Properties of Particle Dampers Systems	MD25_6
	<u>Felipe Klein Fiorentin</u> (Federal University of Santa Catarina, Campus Joinville, Brazil), Arthur Prieto, Anelize Zomkowski Salvi, Andrea Piga Carboni, Thiago Antonio Fiorentin	

12:40	Mechanics of Tire-Terrain Interaction <u>Massimo Cavacece</u> (University of Cassino and Southern Latium, Cassino, Italy)	MD25_9
13:00	LUNCH BREAK (Coffee Lounge)	
	Session 3: Machine Elements & Mechanisms I (Chair: <u>Andrea P. Carboni</u> , Federal University of Santa Catarina, Campus Joinville, Brazil; <u>E. Marques</u> , University of Porto, Porto, Portugal)	
	Room Bo32	
14:00	PLENARY LECTURE: Computational Approaches for Better Gear Performance and Design <u>Alfonso Fuentes-Aznar</u> (Rochester Institute of Technology: Rochester, New York, US)	
14:40	Fundamental Design of a Tool Holder with an Internal Cooling Channel <u>S. Wakiya</u> (Kanagawa University, Yokohama, Kanagawa, Japan), Y. Nakao	MD25_10
15:00	Hysteresis in Torsion Springs C. Bono, <u>H. Font</u> (ICA, Université de Toulouse, UPS, INSA, ISAE-SUPAERO, MINES-ALBI, CNRS, France), M. Paredes	MD25_13
15:20	Role of Granular Layer Thickness in Impact Absorption <u>B. Panić</u> (University of Ljubljana, Faculty of Mechanical Engineering, Slovenia), S. Avdić, M. Nagode, J. Klemenc, I. Emri, S. Oman	MD25_14
15:40	Geometry Optimization to Improve Helical Springs Reliability: An Approach based on Material Variabilities <u>G. Cadet</u> (ICA, UPS, INSA, ISAE-SUPAERO, MINES-ALBI, CNRS, Toulouse, France), M. Paredes	MD25_12
16:00	COFFEE BREAK (Coffee Lounge)	
	Session 4: Machines I (Chair: <u>Alfonso Fuentes-Aznar</u> , Rochester Institute of Technology, USA; <u>Alireza Akhavan-Safar</u> , Institute of Science and Innovation in Mechanical and Industrial Engineering (INEGI), Porto, Portugal)	
	Room Bo32	
16:20	Development of an Inertial Test Bench for Brake Pad Particulate Matter Emission Analysis V. G. G. Catão, L. Bernardino, A. S. Zomkowski , F. K. Fiorentin ,T. A. Fiorentin, <u>A. P. Carboni</u> (Federal University of Santa Catarina, Campus Joinville, Brazil)	MD25_16
16:40	Control of servo-hydraulic systems using dynamics found in Black Holes Rodrigo M. C. Bernardo (Mechanical Engineering Department, University of Aveiro, Portugal), Delfim F. M. Torres, Carlos A. R. Herdeiro, Marco P. Soares dos Santos	MD25_44
17:00	Benchmarking and Establishment of Design Guidelines for the Development of Alternative Radiator Guards for Off-Road Motorcycles <u>A. F. V. Pedroso</u> (CIDEM, ISEP, Polytechnic of Porto, Portugal), F. J. G. Silva, R. D. S. G. Campilho, Naiara P. V. Sebbe, Rúben D. F. S. Costa, César B. Santos	MD25_18
17:20	Easy Quality Control at Pick & Place <u>A. A. Santos</u> (ISEP-Polytechnic of Porto, Portugal), M. Pinto, I. Azevedo, F. Pereira, A. F. Silva, P. Silva, C. Felgueiras	MD25_19
17:40	Development and validation of an underwater image perception system <u>D. Moreira</u> (INESC TEC, Faculdade de Engenharia, Universidade do Porto, Portugal), J. M. M. Dionísio, J. Bessa, P. Pereira, R.D.S.G. Campilho, A. Pinto	MD25_43
18:00	Leveraging LoRaWAN for Industrial IoT: Opportunities and Challenges <u>G. Mendes</u> (Faculdade de Engenharia da Universidade do Porto, Portugal), D. Sousa, A. M. Lopes	MD25_20
18:20	Guided visit to the AJPU Lab. (room M103)	

19:00

RECEPTION & Posters Session (Coffee Lounge)

Poster 1	Performance of a Split Hopkinson Pressure Bar with a Novel Pneumatic Impactor	MD25_23
	<u>R. J. C. Carbas</u> (Instituto de Ciência e Inovação em Engenharia Mecânica e Engenharia Industrial (INEGI), Porto, Portugal), C. M. da Silva, A. M. Lopes, E. A. S. Marques, L. F. M. da Silva	
Poster 2	Development of Novel Testing Equipment for Mechanical Characterization of Complex Materials	MD25_26
	<u>E. A. S. Marques</u> (Faculdade de Engenharia, Universidade do Porto, Portugal), R. J. C. Carbas, C. M. da Silva, A. M. Lopes, L. F. M. da Silva	
Poster 3	Development of a Unified Specimen for Direct Generation of Cohesive Zone Law Data of Adhesives	MD25_27
	<u>D. S. Correia</u> (Instituto de Ciência e Inovação em Engenharia Mecânica e Engenharia Industrial (INEGI), Porto, Portugal), E. A. S. Marques, R. J. C. Carbas, L. F. M. da Silva	
Poster 4	Development and Evaluation of a Flexible Tool for Hole Hemming of Dissimilar Lightweight Materials	MD25_17
	<u>M. M. Kasaei</u> (Institute of Science and Innovation in Mechanical and Industrial Engineering (INEGI), Porto, Portugal), E. A. S. Marques, R. J. C. Carbas, L. F. M. da Silva	
Poster 5	Hele-Shaw Cell Design for Experimental Analysis of Adhesive Flow	MD25_15
	<u>P. M. S. Almeida, A. Akhavan-Safar</u> (Institute of Science and Innovation in Mechanical and Industrial Engineering (INEGI), Porto, Portugal), R. J. C. Carbas, E. A. S. Marques, J. Hrachova, H. Leenders, L. F. M. da Silva	
Poster 6	7 DoF Parallel Robot Controller Based on Neural Networks and the Model of Hierarchical Complexity	MD25_30
	<u>A. L. Cunha, F. Silva, S. Leite, A. M. Lopes, A. R. Silva</u> (Faculty of Engineering of the University of Porto, Portugal)	
Poster 7	Compact and Cost-Effective Educational Kit to Teach Key Concepts of Industry 4.0 and Industrial Internet of Things (IIoT), Using the FINDER OPTA Smart Programmable Logic Controller (PLC)	MD25_8
	<u>Filipe Pereira</u> (School of Engineering of Porto (ISEP), Polytechnic of Porto, Portugal), Adriano Santos, António Silva, Carlos Felgueiras, and António Ramos	
Poster 8	Study of Adhesive Squeezing Flow using a Modified Hele-Shaw Cell Device	MD25_48
	<u>P.M.S. Almeida</u> (Faculdade de Engenharia, Universidade do Porto, Portugal), A. Akhavan-Safar, D. Garcia, R.J.C. Carbas, E.A.S. Marques, J. Hrachova, H. Leenders, L.F.M. da Silva	
Poster 9	Development of a thermo-electrical setup for testing electric vehicle battery interconnections	MD25_49
	<u>V.P.N.C. Henriques</u> (Faculdade de Engenharia, Universidade do Porto, Portugal), M.M. Kasaei, R.J.C. Carbas, E.A.S. Marques, L.F.M. da Silva	
Poster 10	Automation Workbench to Developing i4.0 Skills	MD25_36
	<u>I. Azevedo</u> (ISEP-Polytechnic of Porto, Portugal), M. Pinto, F. Pereira, A. A. Santos, A. F. Silva, P. Silva, C. Felgueiras	
Poster 11	A High Speed Infrared Camera Array Based Positioning and Its Application to Indoor Robotics STEM Education	MD25_52
	<u>Tai Oi-Tai</u> (Department of Electronics, Telecommunications and Informatics of University of Aveiro, Portugal), Carla Raquel Castro da Rocha Madureira, Pedro Nicolau Faria da Fonseca, Tam Kam-Weng	

Time	Friday 12 September 2025
Session 5: Machines II	
(Chair: Manuel Paredes, ICA, Université de Toulouse, UPS, INSA, ISAE-SUPAERO, MINES-ALBI, CNRS, France; Mehdi M. Kasaei, Institute of Science and Innovation in Mechanical and Industrial Engineering (INEGI), Porto, Portugal)	
Room Bo32	
08:40	PLENARY LECTURE: The Role of Operational Experimentation in the Design of Unmanned Maritime Vehicles João Tasso de Sousa (Head of the Underwater Systems and Technologies Laboratory - LSTS, Faculty of Engineering, University of Porto, Portugal)
09:20	A Design Method of Rotor Profile of Screw Pump MD25_21 K. Kawasaki (Sanjo City University, Kamisugoro, Japan), M. Nagai
09:40	A Floating Base with Reconfigurable Geometry for a Drone Supporting USV MD25_22 J. Bessa (INESC TEC, Faculdade de Engenharia, Universidade do Porto, Portugal), P. Pereira, D. Moreira, J.M.M Díoniso, R.D.S.G. Campilho, A. Pinto
10:00	Extending Bearing Design Standards: Smearing Risk Assessment via Transient Simulation MD25_11 P. Wingertszahn, J. Müller, O. Koch, M. Carstensen (RPTU University of Kaiserslautern-Landau, Kaiserslautern, Germany)
10:20	Optimizing Micro-Geometry Modifications for Enhanced Performance and Durability in Geared Rotary Actuators MD25_24 A. Fuentes-Aznar (Rochester Institute of Technology (RIT), Rochester, NY, USA), I. González-Pérez
10:40	COFFEE BREAK (Coffee Lounge)
Session 6: Machine Elements & Mechanisms II	
(Chair: Adriano Santos, School of Engineering, Polytechnic of Porto, Portugal; R.D.S.G. Campilho, School of Engineering, Polytechnic of Porto, Portugal)	
Room Bo32	
11:00	Vibrations of a Small-caliber Weapon System on a Four-wheeled Chassis of a Small Drone MD25_47 N.B. Dang, M. Macko (University of Defence, Brno, Kounicova, Czech Republic), V.V. Bien, B.V. Dung
11:20	Improvement of the production process for machined and bent tubes: Study of stretching in tube bending MD25_35 Bruno Ribeiro, Eurico Seabra (Department of Mechanical Engineering, University of Minho, Guimarães, Portugal), António Lopes
11:40	Efficiency Improvement on Grease Injection Process in Control Cables for the Automotive Industry MD25_28 J. P. P. S. T. Ferreira, R. D. S. G. Campilho (CIDEM, ISEP – School of Engineering, Polytechnic of Porto, Portugal), F. J. G. Silva
12:00	Design of an Automated Equipment with Interchangeable Modules for Electronic Board Testing MD25_29 D. F. A. Neves, R.D.S.G. Campilho (CIDEM, ISEP – School of Engineering, Polytechnic of Porto, Portugal), F. J. G. Silva
12:20	Design and Implementation of a Microwave-Based Angular Displacement Sensor with Analog to Digital Conversion in IoT-Elevator Systems MD25_51 Kam-Weng Tam (Faculty of Science and Technology of University of Macau, China), Chi-Hou Chio, Desen Li, Quan Xue
12:40	Multi Inverted Pendulum Controller Based on Neural Networks and the Model of Hierarchical Complexity MD25_31 A. L. Cunha, F. Silva, S. Leite, A. M. Lopes, A. R. Silva (Faculty of Engineering of the University of Porto, Portugal)
13:00	LUNCH BREAK (Coffee Lounge)

Session 7: Machine Automation & Testing III

(Chair: Luciano E. Chiang, Pontificia Universidad Católica de Chile, Chile; Filipe Pereira, School of Engineering of Porto (ISEP), Polytechnic of Porto, Portugal)

Room Bo32

14:00	PLENARY LECTURE: Making Optimization Work for Machine Design—No Black Magic Required Stijn Derammelaere (Department of Electromechanical Engineering, University of Antwerp, Belgium)	
14:40	Compaction System for Packaging Recycling D. Meireles, A. A. Santos (ISEP-Polytechnic of Porto, Portugal), A. F. Silva, F. Pereira, P. Silva, C. Felgueiras	MD25_32
15:00	Multi-injection Mould Design for Automotive Components Using Two Distinct Polymeric Materials A. F. V. Pedroso (CIDEM, ISEP, Polytechnic of Porto, Portugal), F. J. G. Silva, R. D. S. G. Campilho, Naiara P.V. Sebbe, Rúben D. F. S. Costa, César B. Santos	MD25_33
15:20	Study and Design of Automation of the Crutches Assembly Process João Cunha, Eurico Seabra (Department of Mechanical Engineering, University of Minho, Guimarães, Portugal), António Lopes	MD25_34
15:40	Influence of Beam Oscillation on Microstructural Evolution in Laser Welding of DP1000 Dual-Phase Steel Eva S.V. Marques (TEMA—Centre for Mechanical Technology and Automation, Department of Mechanical Engineering, University of Aveiro, Portugal), António B. Pereira, Francisco J.G. Silva	MD25_50
16:00	COFFEE BREAK (Coffee Lounge)	
<h2>Session 8: Machines III</h2> <p>(Chair: A. M. Lopes, University of Porto, Portugal; L. F. M. da Silva, University of Porto, Portugal)</p>		
Room Bo32		
16:20	Teaching Kit for Collaborative Robotics M. Pinto (ISEP-Polytechnic of Porto, Portugal), I. Azevedo, F. Pereira, A. F. Silva, P. Silva, C. Felgueiras, A. A. Santos	MD25_37
16:40	Event-based imaging for non-contact vibration Measurement Francisco Sousa, Francisco Afonso, Pedro Sousa (Faculty of Engineering of the University of Porto, Portugal), Susana Dias, Paulo Tavares, Pedro Moreira	MD25_38
17:00	Artificial Intelligence-driven Approaches for Robotic Control: Beyond the Classical Methods F. M. Silva (INEGI - Instituto de Ciência e Inovação em Engenharia Mecânica e Engenharia Industrial, Porto, Portugal), A. M. Lopes, A. R. Silva	MD25_25
17:20	Nonlinear Multi-DOF Absorber Based on Nonlinear Springs and Voice-coil Actuators Zbyněk Šika (Faculty of Mechanical Engineering, Czech Technical University in Prague, Czech Republic), Karel Kraus, Jan Krivošej, Jakub Švadlena, Petr Beneš	MD25_40
17:40	Design and Evaluation of a Variable Buoyancy System for AUVs A. P. Carboni (Federal University of Santa Catarina, Campus Joinville, Brazil), C.G. Valin, L. G. Barcaro, A. Z. Salvi, Nuno A. Cruz, T. A. Fiorentin, F. K. Fiorentin	MD25_41
18:00	Current-based control of a tendon-hobbed-pulley thumb-index prosthesis Patrícia Gomes, João Nunes, Susana Dias, Pedro Sousa (Faculty of Engineering of the University of Porto, Portugal), Paulo Tavares, Pedro Moreira	MD25_42
20:00	MD2025 BANQUET (UVA by Calem restaurant)	